

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L21	2	JP-2000288974-\$.did.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/06 14:27
L22	2	JP-2000288968-\$.did.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/06 14:27
L23	1	JP-04075887-\$.did.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/06 14:27
L24	2	WO-9942257-\$.did.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2005/10/06 14:27
L25	2	WO-9201539-\$.did.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2005/10/06 14:27
L26	6	"5083073".pn. "5446835".pn. "5523663".pn. "4725965".pn. "4985846".pn. "5297238".pn.	US-PGPUB; USPAT	OR	ON	2005/10/06 14:27
L27	1	("5,617,335").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2005/10/06 14:27
L28	1	("4,727,471").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2005/10/06 14:27
L29	5	JP-05127722-\$.did. JP-07270137-\$.did. JP-07319525-\$.did.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/06 14:27
L30	1	("4785528").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2005/10/06 14:27
L31	241	(382/152).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2005/10/06 14:27
L32	41	((382/152).CCLS.) and robot	US-PGPUB; USPAT	OR	ON	2005/10/06 14:27
L33	66	((382/151).CCLS.) and robot	US-PGPUB; USPAT	OR	ON	2005/10/06 14:27

L34	8	arimatsu-taro.in.	US-PGPUB; USPAT	OR	ON	2005/10/06 14:27
L35	210	watanabe-atsushi.in.	US-PGPUB; USPAT	OR	ON	2005/10/06 14:27
L36	8	382/141-154;901/47.ccls. and watanabe-atsushi.in.	US-PGPUB; USPAT	OR	ON	2005/10/06 14:27
L37	112	(robot) same (plural\$3 or multiple or dual or two or several or many) adj (video or camera or CCD or image or visual) same (workpiece or work-piece or work adj piece or part or model)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/06 14:27
L38	17	((382/154).CCLS.) and (reference or register\$3 or registration or teach\$3 or train\$3 or learn\$3) with (object or model or part or workpiece or work-piece or work adj piece) same robot	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/06 14:27
L39	142	(robot) same (video or camera or CCD or image or visual) same (predetermined or known or specifi\$2 or determined) near distance	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/06 14:27
L40	74	robot same (2-D or two-D or two-dimension\$2 or "2"-dimension\$2 or bi-dimensional or (two or "2") adj dimension\$2) with distance	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/06 14:27
L41	30	robot same (reference or register\$3 or registration or teach\$3 or train\$3 or learn\$3) same (video or camera or CCD or image or visual) same (predetermined or known or specifi\$2 or determined) near distance	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/06 14:27
L42	69	((901/47).CCLS.) and (registration or teach\$3 or train\$3 or learn\$3) with (model or part or workpiece or work adj piece)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/06 14:27
L43	175	(382/153).CCLS.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/10/06 14:27

L44	230	("382"/\$.ccls. "348"/\$.ccls. "356"/\$.ccls. "700"/\$.ccls. "901"/\$.ccls.) and robot\$3 same (camera or CCD or imag\$3 or video) same (position\$3 or locat\$4 or (three or "3") adj dimension\$2 or 3D or coordinate) with (orientation or posture or attitude or pose) with (object or workpiece or work adj piece or part or bin or pile\$1 or article or body)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/06 14:27
L45	52	robot\$3 same (camera or CCD or imag\$3 or video) same (orientation or posture or attitude or pose) with (object or workpiece or work adj piece or part or bin or pile\$1 or article or body) same (reference or model or register\$3 or registration or template or stored) with (compar\$5 or match\$3 or correlat\$3 or correspond\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/06 14:27
L46	3	("5446835" "5579444" "5845048").pn.	USPAT	OR	OFF	2005/10/06 14:31